

International Spring School Statistical Thermodynamics, Santiago de Chile
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[Lecture 20](#)

Accounting for polarisation effects in bio-molecular simulation

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Inclusion of polarisability in molecular models

A. Why polarisability ?

B. Six aspects

C. Charge-on-spring (COS) models

Inclusion of polarisability in molecular models

A. Why polarisability ?

1. Effects of polarisability

B. Six aspects

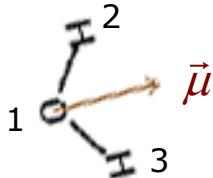
C. Charge-on-spring (COS) models

Effects of polarisability

I Liquids, water

1. Dipole moment of a water molecule:

$$\vec{\mu} = \sum_{i=1}^3 q_i \vec{r}_i$$



gas phase = 1.85 Debye
liquid phase \sim 2.5 Debye

water molecule is polarised when immersed in water

2. Polarisation energy of liquid water

potential energy: $\sim 10 \text{ kJ/mol}$
 42 kJ/mol

polarisation energy $\sim 25\%$

$1 \text{ eV} = 97 \text{ kJ/mol}$

or $1 \text{ kJ/mol} = 0.01 \text{ eV}$

$1 \text{ kcal/mol} = 4.184 \text{ kJ/mol}$ or $1 \text{ kJ/mol} = 0.24 \text{ kcal/mol}$

Effects of polarisability

3. Macroscopic polarisation as function of the frequency ω of the oscillating electric field \vec{E}

the dielectric permittivity $\varepsilon_r(\omega)$

is dependent on the frequency ω

of the oscillating field $\vec{E}(\omega)$

liquid water $\varepsilon_r(0) = \varepsilon_r(\text{static}) = 78$ electronic + orientation

$\varepsilon_r(\infty) = \varepsilon_r(\text{infinite freq.}) \approx 2 - 5$ only electronic

Consequence: gas phase water models

(e.g. derived using quantum-mechanical models)

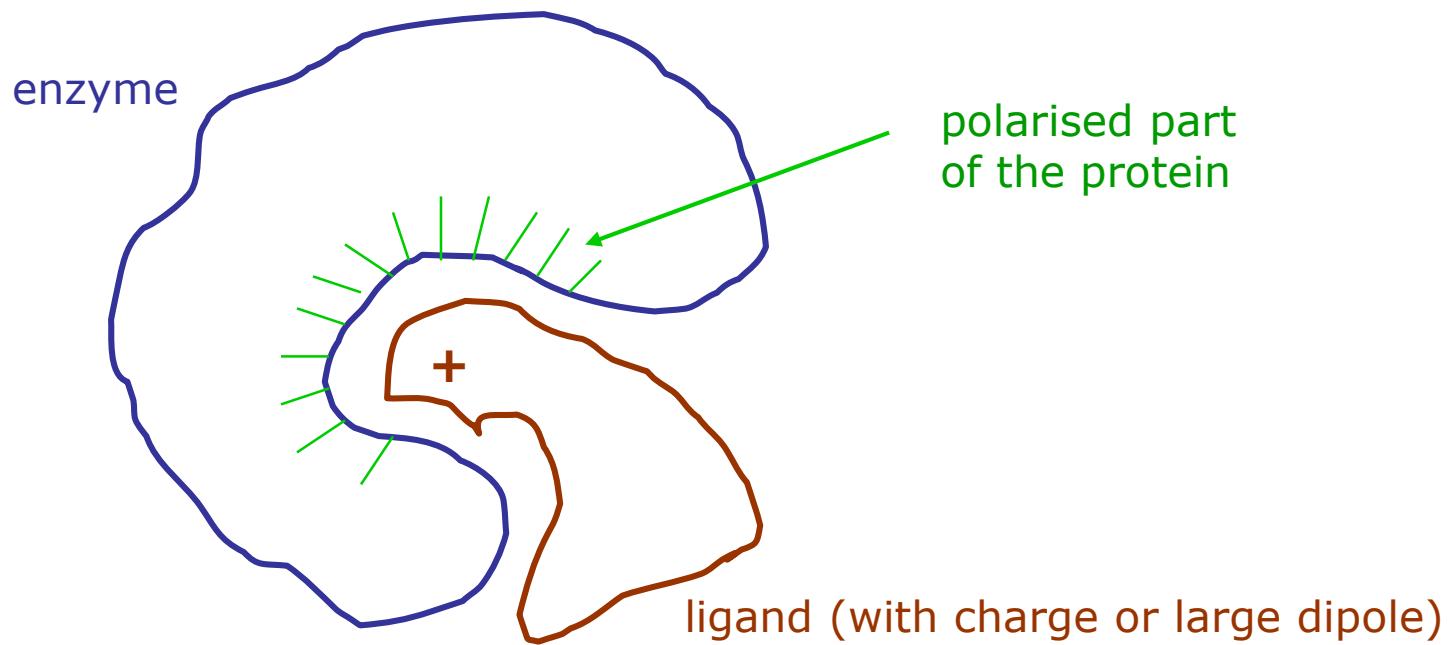
**will not represent liquid water,
if explicit polarisation is not included**

Effects of polarisability

II Lipids and proteins in membranes

Carbon atoms of lipids can get polarised upon protein insertion

III Proteins, ligand binding



Protein can get polarised upon ligand binding

Inclusion of polarisability in molecular models

A. Why polarisability ?

- 1. Effects of polarisability**
- 2. Limitations of non-polarisable force fields**

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Limitations of non-polarisable force fields

1. Solvation of polar amino-acid side-chain analogs

One set of atomic charges and van der Waals parameters cannot reproduce both:

heat of vaporisation
of the liquid } and { free energy of solvation in
polar solvent: water

GROMOS **53A5** parameters GROMOS **53A6** parameters

due to the different polarisability of these two environments.

Free energy of solvation in apolar solvent, cyclohexane, is compatible with both using a non-polarisable force field.

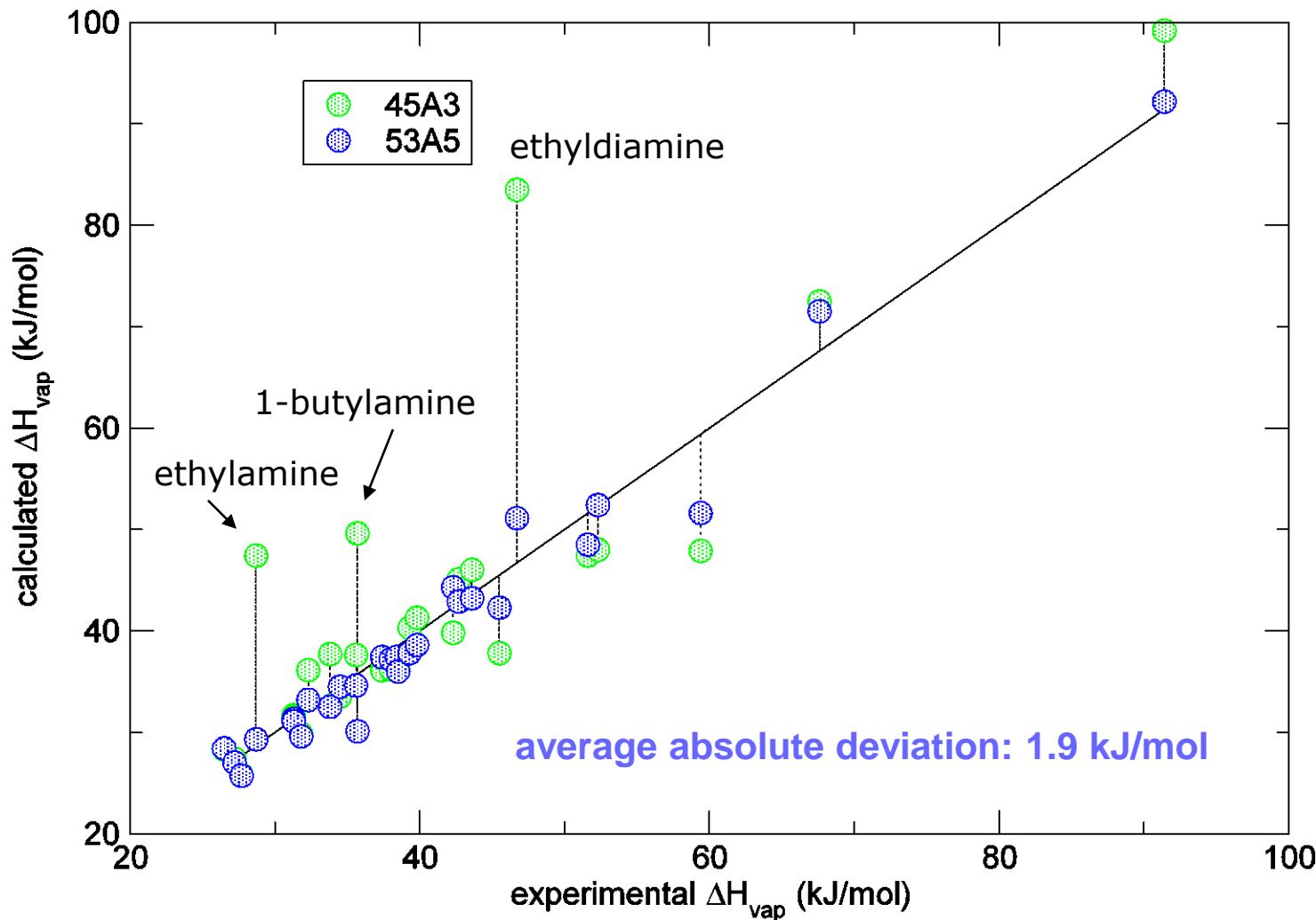
2. Solvation of dimethylether (DME)

Polarisable models yield better (free) energies (of solvation)

3. Hydrophobic solvation in water – ethylene glycol mixtures

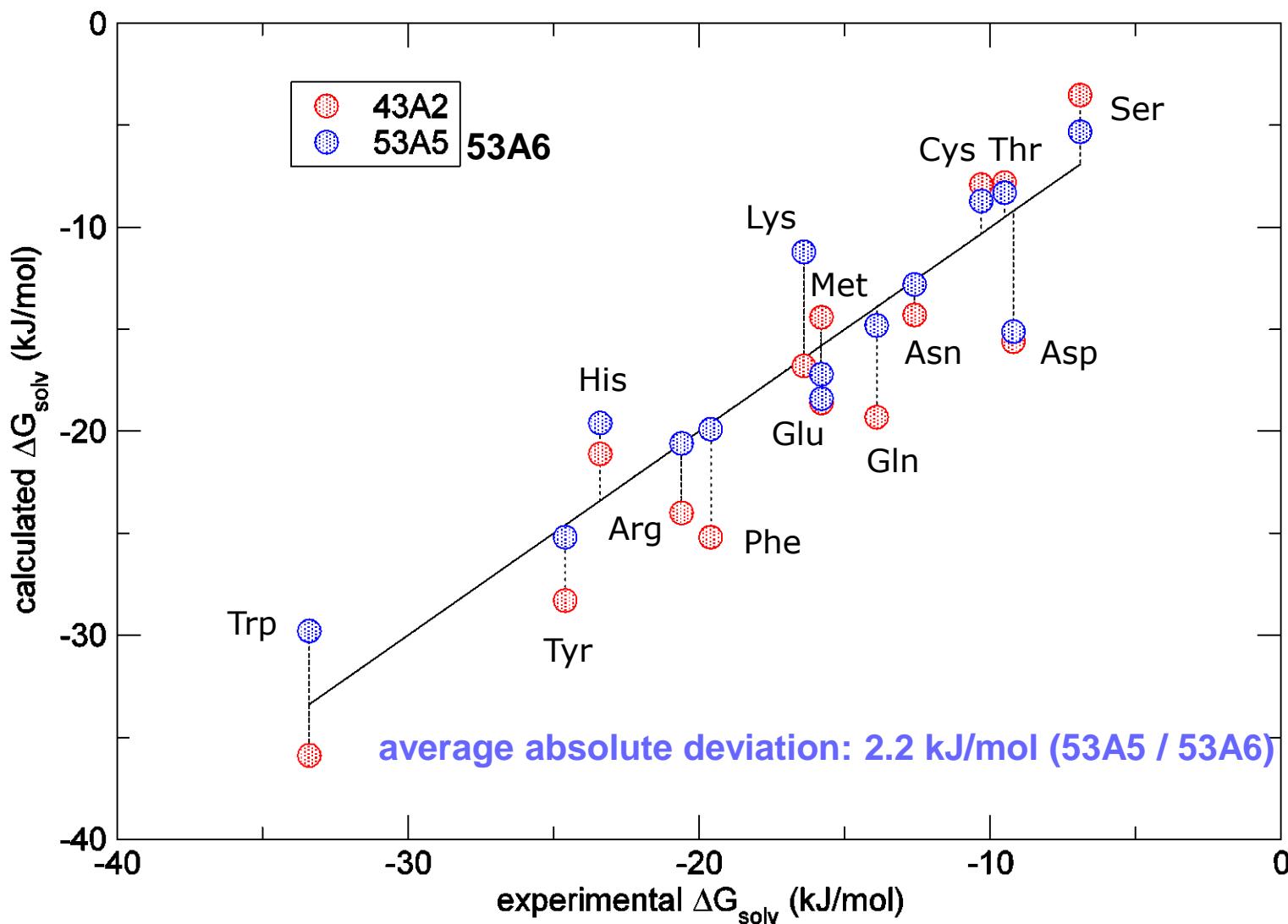
Polarisable models can reproduce the maximum in the free enthalpy of solvation as function of ethylene glycol mole fraction

Heat of vaporization for pure liquids



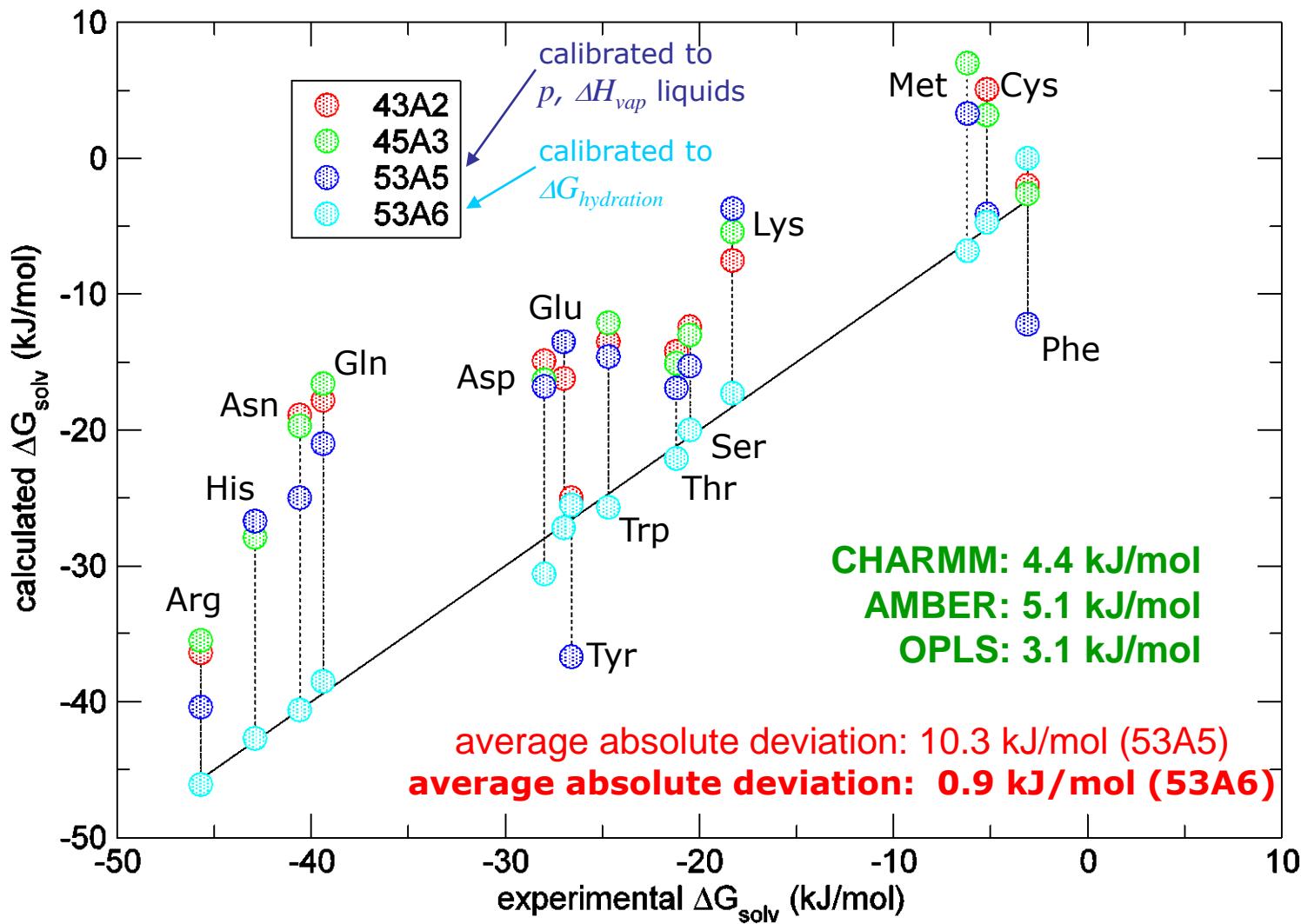
Free energy of solvation in cyclohexane

amino acid analogues (polar)

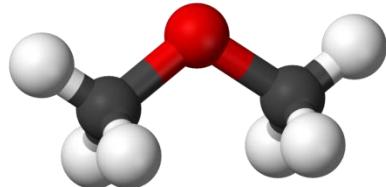


Free energy of solvation in water

amino acid analogues (polar)



Use of polarisable force fields



A **polarisable** force field for
dimethyl ether, cyclohexane and **water**

	pure DME	1 DME in cyclohexane	1 DME in water
	$\Delta H_{\text{vap}} [\text{kJ mol}^{-1}]$	$\Delta G_{\text{solv}} [\text{kJ mol}^{-1}]$	$\Delta G_{\text{hydr}} [\text{kJ mol}^{-1}]$
Experiment	21.7	~ -9.5	~ -7.6
DME _{nonpol} /solv _{nonpol}	21.3	-9.3	-3.2
DME _{pol} /solv _{nonpol}	21.0	-8.3	-9.6
DME _{pol} /solv _{pol}	21.0	-9.9	-7.0

Non-polarisable force field has difficulty reproducing solvation in **non-polar and polar** solvent.

Polarisable DME improves the solvation in **water**,
but degrades solvation in **cyclohexane**.

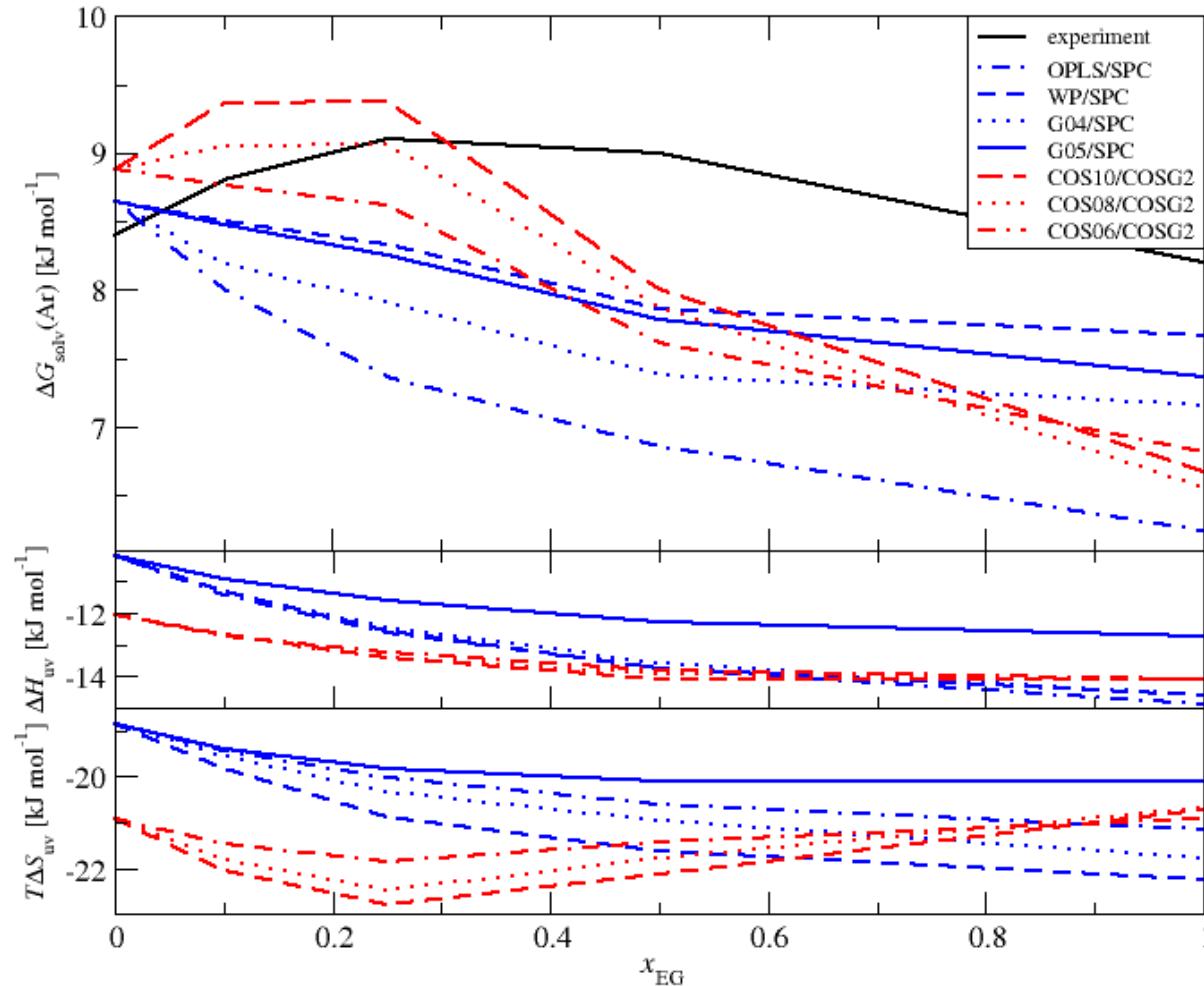
Polarisable solvent increases the **transferability**
between different environments further.

Hydrophobic hydration (argon) in water-ethylene-glycol mixtures

Non-polarisable models versus polarisable models

Free enthalpy
of solvation

Black:
experiment



Solute-solvent
enthalpy
of solvation

Solute-solvent
entropy
of solvation

Only polarisable models reproduce the experimental trend

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Accounting for polarisation in molecular simulation

Polarisation

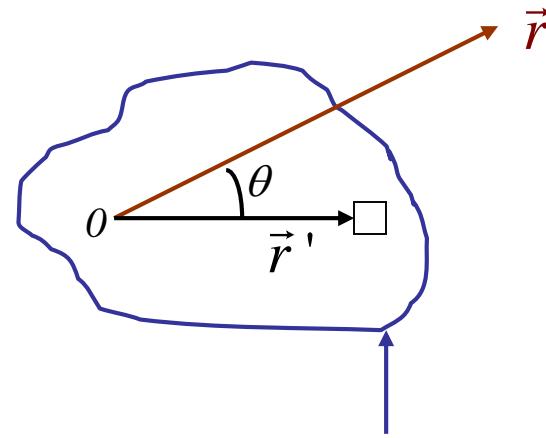
Change the *multipole moments* $\mu^{(n)}$ of a charge distribution due to an (applied) *electric field* \vec{E}

monopole:	charge	q	}	of charge distribution
dipole:	dipole	$\vec{\mu}$		
quadrupole:	...			
octupole:	...			

Potential and field of a charge distribution

Coulomb potential

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d\vec{r}',$$



Series expansion of the integrand

$$\frac{1}{|\vec{r} - \vec{r}'|} = \left[(x - x')^2 + (y - y')^2 + (z - z')^2 \right]^{-\frac{1}{2}}$$

$$= \left[x^2 + y^2 + z^2 - 2(xx' + yy' + zz') + x'^2 + y'^2 + z'^2 \right]^{-\frac{1}{2}}$$

$$= \left[r^2 - 2\vec{r} \cdot \vec{r}' + r'^2 \right]^{-\frac{1}{2}}$$

$$= \frac{1}{r} \left[1 - \frac{2\vec{r} \cdot \vec{r}'}{r^2} + \left(\frac{r'}{r} \right)^2 \right]^{-\frac{1}{2}}$$

$$= \text{assume } |\vec{r}'| \ll |\vec{r}| \text{ and use } [1+x]^{-\frac{1}{2}} = 1 - \frac{1}{2}x + \frac{3}{8}x^2 - \frac{5}{16}x^3 + \dots$$

$\rho(\vec{r}')$ = charge density

Potential and field of a charge distribution

Series expansion of the integrand

$$\frac{1}{|\vec{r} - \vec{r}'|} = \frac{1}{r} \left[1 + \frac{\vec{r} \cdot \vec{r}'}{r^2} - \underbrace{\frac{1}{2} \left(\frac{r'}{r} \right)^2}_{\text{I}} + \frac{3}{2} \frac{(\vec{r} \cdot \vec{r}')^2}{r^4} - \frac{3}{2} \frac{(\vec{r} \cdot \vec{r}') r'^2}{r^4} + \frac{3}{8} \left(\frac{r'}{r} \right)^4 \dots \right]$$

I II

$$1 \quad \frac{r'}{r}$$

III

$$\left(\frac{r'}{r} \right)^2$$

IV

$$\left(\frac{r'}{r} \right)^3$$

Term I: monopole

$$\varphi^I(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r} \int \rho(\vec{r}') d\vec{r}' = \frac{1}{4\pi\epsilon_0} \frac{q}{r} \quad q = \text{charge}$$

Term II: dipole

$$\varphi^{II}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{r}}{r^3} \cdot \int \vec{r}' \rho(\vec{r}') d\vec{r}' = \frac{1}{4\pi\epsilon_0} \frac{\vec{\mu} \cdot \vec{r}}{r^3} \quad \mu = \text{dipole-moment}$$

Term III: quadrupole

$$\begin{aligned} \varphi^{III}(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} \int \frac{1}{2} [3 \cos^2 \theta - 1] r'^2 \rho(\vec{r}') d\vec{r}' \\ &= \frac{1}{4\pi\epsilon_0} \frac{Q(\theta)}{r^3} \quad Q = \text{quadrupolemoment} \end{aligned}$$

Potential and field of a charge distribution

Electric field

differentiate φ with respect to \vec{r} , take minus sign:

$$\text{Term I: } E^I(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \frac{\vec{r}}{r} = \frac{q\vec{r}}{4\pi\epsilon_0 r^3}$$

$$\text{Term II: } E^{II}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left[-\frac{\vec{\mu}}{r^3} + \frac{3\vec{r}(\vec{\mu} \cdot \vec{r})}{r^5} \right] = \underbrace{\frac{1}{4\pi\epsilon_0} \frac{1}{r^3} \left[\frac{3\vec{r}\vec{r}}{r^2} - 1 \right]}_{\text{dipole tensor } \vec{T}} \cdot \vec{\mu}$$

dipole tensor \vec{T}

Macroscopic description of polarisation

Continuum with relative dielectric permittivity ϵ_r

or susceptibility χ

- **dielectric displacement:** $\vec{D} = \epsilon_0 \epsilon_r \vec{E}$

- **polarisation:** $\vec{P} = (\epsilon_r - 1) \epsilon_0 \vec{E} = \chi \vec{E}$

- **Coulomb energy:** $U(r_i, r_j) = \frac{1}{4\pi\epsilon_0 \epsilon_r} \frac{q_i q_j}{|r_i - r_j|}$

Accounting for polarisation in molecular simulation

Distinguish:

1. Dipole moment versus other multipole moments

- monopole generally does not change (charge conservation)
- dipole term then dominates expansion

2. Homogeneous versus inhomogenous fields

$$\vec{E} = \vec{E}(\vec{r}) \quad \vec{E} \text{ varies with } \vec{r}$$

3. Linear versus non-linear dependence of induced moment on field \vec{E}

$$\vec{\mu} = \vec{\alpha} \vec{E} \quad \vec{\mu} = \vec{f}(\vec{E})$$

Accounting for polarisation in molecular simulation

Distinguish:

4. Isotropic versus anisotropic polarisation

$$\vec{\mu} = \alpha \vec{E}$$

$$\begin{array}{c} \vec{E} \\ \longrightarrow \\ \vec{\mu} \end{array} \quad \alpha = \text{scalar}$$

$\vec{\mu}$ in direction of field \vec{E}

$$\vec{\mu} = \vec{\alpha} \vec{E}$$

$$\begin{array}{c} \vec{E} \\ \searrow \\ \vec{\mu} \end{array} \quad \vec{\alpha} \text{ is a tensor}$$

5. Permanent dipoles versus induced dipoles

gas phase

due to surroundings in the condensed phase

Various approximations used

1. **linear dipole** polarisation in a **non-homogeneous electric field**

$$\vec{\mu}(\vec{E}) = \vec{\alpha}\vec{E} + \underbrace{\frac{1}{3}\vec{\alpha}'\vec{\nabla}\vec{E} + \frac{1}{15}\vec{\alpha}''\vec{\nabla}\vec{\nabla}\vec{E}}_{\text{non-uniform part, neglected in homogeneous field approximation}} + \dots$$

2. **linear dipole** polarisation in a **homogeneous electric field**

$$\vec{\mu}(\vec{E}) = \vec{\alpha}\vec{E}$$

3. **non-linear dipole** polarisation in a **homogeneous electric field**

$$\vec{\mu}(\vec{E}) = (\vec{\alpha} + \underbrace{\vec{\beta}\vec{E} + \frac{1}{2}\vec{\gamma}\vec{E}\vec{E}}_{\text{non-linear part, neglected in linear response approximation}} + \dots) \vec{E}$$

Various approximations used

4. isotropic linear dipole polarisation in a homogeneous field

$$\begin{pmatrix} \mu_x \\ \mu_y \\ \mu_z \end{pmatrix} = \underbrace{\begin{pmatrix} \alpha_{xx} & \alpha_{xy} & \alpha_{xz} \\ \alpha_{yx} & \alpha_{yy} & \alpha_{yz} \\ \alpha_{zx} & \alpha_{zy} & \alpha_{zz} \end{pmatrix}}_{\text{tensor character, neglected in isotropic polarization approximation}} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix}$$
$$\begin{pmatrix} \mu_x \\ \mu_y \\ \mu_z \end{pmatrix} = \alpha \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix}$$

scalar

5. no (explicit) induced dipoles

$$\vec{\mu}^{\text{permanent}} \neq \vec{0}$$

↑
may include mean polarisation

$$\vec{\mu}^{\text{induced}} (\vec{E}) = \vec{0}$$

neglect of induced polarisation

Inclusion of polarisability in molecular models

A. Why polarisability ?

- 1. Effects of polarisability**
- 2. Limitations of non-polarisable force fields**

B. Six aspects

- 1. Definition, distinctions, approximations**
- 2. Mechanisms**

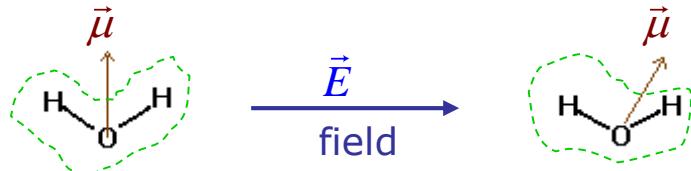
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Molecular mechanisms of polarisation

1. Electronic:
2. Geometric:
3. Orientational:

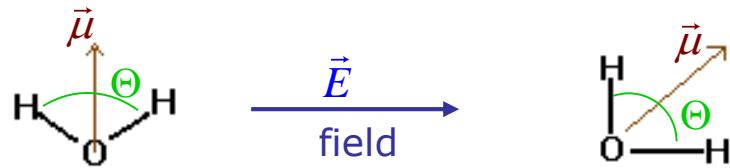
redistribution of electrons over atoms/molecules
change of geometry of a molecule
realignment of molecule

Ad 1:



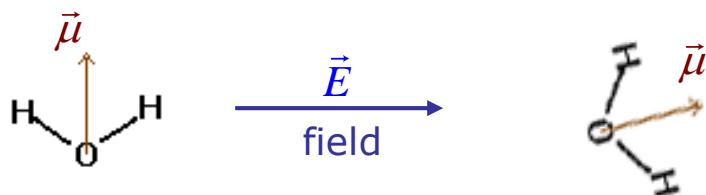
electron density shifts to left
due to \vec{E}

Ad 2:



bond angle Θ narrows
due to \vec{E}

Ad 3:



molecular orientation changes
due to \vec{E}

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C. Charge-on-spring (COS) models

Modelling of polarisability in molecular simulation

1. Mean-field models:

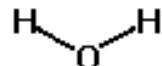
implicit polarisation

permanent dipole moment of a molecule is **enhanced** from gas phase value to the condensed phase value

for example:

$$\mu_{gas} = 1.85 \text{ Debye}$$

water



$$\mu_{SPC} = 2.27 \text{ Debye}$$

SPC (simple point charge) model for ***liquid*** water

**good model for homogeneous environment,
but not for inhomogeneous surroundings**

→ H₂O bound to protein or ion or in a membrane

Modelling of polarisability in molecular simulation

2. Explicit, classical polarisation in the molecular model

Introduction of *inducible dipoles* in molecules

- **more expensive**
- **not easy to parameterise**

3. Quantum-mechanical treatment of electronic degrees of freedom

The electron density can be polarised

- **not efficient for condensed phase systems**
e.g. ionic solutions

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- 4. Three types of models, choices to be made, considerations**

C. Charge-on-spring (COS) models

How to introduce classical, explicit polarisability into molecular models for simulation

A. Generating induced dipoles: 3 methods

1. induced *point* dipoles $\vec{\mu}_i$ at sites \vec{r}_i

$$\vec{\mu}_i = \alpha_i \vec{E}(\vec{r}_i)$$

2. changing the size of the (atomic) charges

$$q_j \text{ at } \vec{r}_j \text{ such that } \vec{\mu}_i = \sum_j \Delta q_j \vec{r}_j = \alpha_i \vec{E}(\vec{r}_i)$$

so-called **fluctuation-charge models**

3. changing the geometry of the charge distribution, e.g. by changing the position of virtual charge q_j^v such that

$$\vec{\mu}_i = \sum_j q_j^v \vec{r}_j^v = \alpha_i \vec{E}(\vec{r}_i)$$

for example: **charge-on-spring model (COS)**

How to introduce classical, explicit polarisability into molecular models for simulation

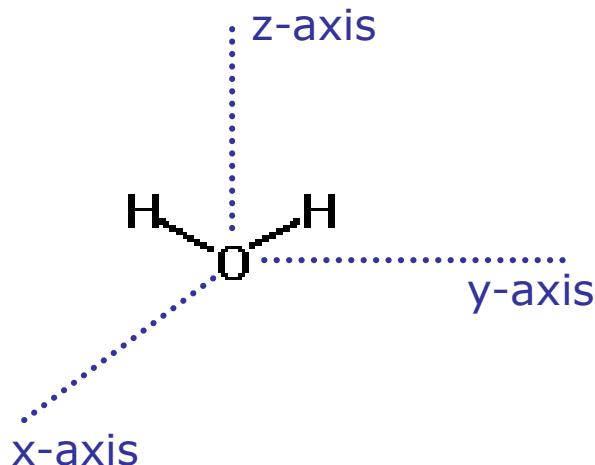
B. Choice of isotropic or anisotropic polarisation

$$\begin{pmatrix} \mu_x \\ \mu_y \\ \mu_z \end{pmatrix} = \begin{pmatrix} \alpha_{xx} & \alpha_{xy} & \alpha_{xz} \\ \alpha_{yx} & \alpha_{yy} & \alpha_{yz} \\ \alpha_{zx} & \alpha_{zy} & \alpha_{zz} \end{pmatrix} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix}$$

Water

$$\left. \begin{array}{l} \alpha_{xx} = 1.415 (4\pi\epsilon_0)10^{-3}\text{nm}^3 \\ \alpha_{yy} = 1.528 (4\pi\epsilon_0)10^{-3}\text{nm}^3 \\ \alpha_{zz} = 1.468 (4\pi\epsilon_0)10^{-3}\text{nm}^3 \end{array} \right\} \alpha = 1.47 (4\pi\epsilon_0)10^{-3}\text{nm}^3$$

off-diagonal elements
experimentally not known



bulk of polarisation effect is captured using *isotropic* polarisation

How to introduce classical, explicit polarisability into molecular models for simulation

C. Choosing the sites of the induced dipoles

- **on atoms of model**
- **on other sites:**
 - on bonds (bond polarisability)
 - on virtual atoms

this may introduce torques

D. Avoid the polarisation catastrophe

If two **inducible dipoles** come spatially **too close to each other**, the dipolar interaction between them mutually **enhances their *induced dipoles to infinity***

for example: water $r_{oo} \geq \left[4\alpha^2 / (4\pi\epsilon_0)^2 \right]^{1/6} \approx 0.144 \text{ nm}$

Remedies:

- damp polarisability at short distances
- **use non-linear polarisation, e.g.** $\mu = \alpha \ln(E+1)$ *sublinear*
 - use smaller, more distributed polarisabilities

Considerations regarding choice of model to represent induced dipoles

Accuracy versus simplicity

1. no induced multipoles beyond dipoles

forces are already 3-rd rank tensors using point dipoles

2. monopoles (charges) are most easy to handle in schemes to compute long-range electrostatic forces

particle-mesh schemes, virial
so: fluctuation-charge or charge-on-spring models

3. rather no rigid virtual sites no anisotropy } may result in torques

4. fluctuation charge models

scaling the charges of a charge distribution
does change all multipoles in a fixed ratio

5. charge-on-spring models

if q_j^v is large, separation \vec{r}_j^v is small
dipole approximation is good, so, other multipoles don't change

The charge-on-spring models are the *simplest* realisations of polarisation

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- 4. Three types of models, choices to be made, considerations**
- 5. Expressions for the energy and forces (point dipoles)**

C. Charge-on-spring (COS) models

Induced point dipoles: expression for the energy

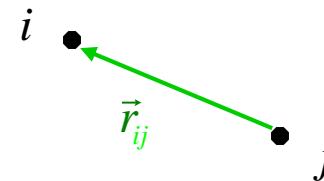
Induced dipoles:

at sites of $i=1, 2 \dots N$ atoms with permanent charges q_i

$$\vec{\mu}_i = \alpha_i \vec{E}_i = \alpha_i \left\{ \vec{E}_i^q + \sum_{\substack{j=1 \\ j \neq i}}^N \vec{T}_{ij} \vec{\mu}_j \right\}$$
$$\underline{M} = \underline{A} \left[\underline{E}^q + \underline{T} \underline{M} \right]$$

Electrostatic field from permanent charges:

$$\vec{E}_i^q = \sum_{\substack{j=1 \\ j \neq i}}^N \frac{1}{4\pi\epsilon_0} \frac{q_j \vec{r}_{ij}}{r_{ij}^3}$$



Dipole tensor:

$$\vec{T}_{ij} = \frac{1}{4\pi\epsilon_0} \frac{1}{r_{ij}^3} \left[\frac{3\vec{r}_{ij}\vec{r}_{ij}}{r_{ij}^2} - 1 \right]$$

Induced point dipoles: expression for the energy

Electrostatic energy:

$$U_{el} = U_{qq} + U_{ind} = U_{qq} + U_{stat} + U_{\mu\mu} + U_{self}$$

$$U_{qq} = \frac{1}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{1}{4\pi\epsilon_0} \frac{q_i q_j}{r_{ij}}$$

$$U_{stat} = - \sum_{i=1}^N \vec{\mu}_i \cdot \vec{E}_i^q$$

$$U_{\mu\mu} = - \frac{1}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \vec{\mu}_i \vec{T}_{ij} \vec{\mu}_j$$

$$U_{self} = \sum_{i=1}^N \int_0^{\vec{\mu}_i} \vec{E}_i \cdot d\vec{\mu}_i' = \sum_{i=1}^N \int_0^{\vec{\mu}_i} \frac{\vec{\mu}_i'}{\alpha_i} d\vec{\mu}_i' = \sum_{i=1}^N \frac{\vec{\mu}_i^2}{2\alpha_i}$$

Induced point dipoles: expression for the forces

At equilibrium:

$$\frac{\partial U_{el}}{\partial \vec{\mu}_i} = 0 \quad \text{or} \quad \vec{\mu}_i = \alpha_i \vec{E}_i$$

Force is the negative gradient of U_{el} :

$$\begin{aligned} \vec{f}_k &= -\frac{\partial U_{el}}{\partial \vec{r}_k} - \sum_{i=1}^N \frac{\partial U_{el}}{\partial \vec{\mu}_i} \cdot \frac{\partial \vec{\mu}_i}{\partial \vec{r}_k} & \frac{\partial U_{el}}{\partial \vec{\mu}_i} = 0 \\ &= -\frac{\partial}{\partial \vec{r}_k} \left[\underbrace{U_{qq} + U_{stat} + U_{\mu\mu}}_{\text{only these contribute}} + U_{self} \right] \end{aligned}$$

Induced point dipoles: expression for the forces

Force is the negative gradient of U_{el} :

$$\begin{aligned}\vec{f}_k &= q_k \vec{E}_k^q + \sum_{i=1}^N \vec{\mu}_i \cdot \frac{\partial \vec{E}_i^q}{\partial \vec{r}_k} + \sum_{\substack{i=1 \\ i \neq k}}^N \frac{\partial}{\partial \vec{r}_k} \left(\vec{\mu}_i \vec{T}_{ik} \vec{\mu}_k \right) \\ &= q_k \vec{E}_k^q + \sum_{i=1}^N \vec{\mu}_i \cdot \frac{\partial}{\partial \vec{r}_k} \left(\sum_{\substack{j=1 \\ j \neq k}}^N \frac{1}{4\pi\epsilon_0} \frac{q_j \vec{r}_{ij}}{r_{ij}^3} \right) \\ &\quad + \sum_{\substack{i=1 \\ i \neq k}}^N \frac{1}{4\pi\epsilon_0} \frac{3}{r_{ik}^5} \left\{ \frac{5}{r_{ik}^2} (\vec{\mu}_i \cdot \vec{r}_{ik}) (\vec{\mu}_k \cdot \vec{r}_{ik}) \vec{r}_{ik} - (\vec{\mu}_i \cdot \vec{\mu}_k) \vec{r}_{ik} - (\vec{\mu}_i \cdot \vec{r}_{ik}) \vec{\mu}_k - (\vec{\mu}_k \cdot \vec{r}_{ik}) \vec{\mu}_i \right\}\end{aligned}$$

if the induced dipoles $\vec{\mu}_i$ are known, force \vec{f}_k is known

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B. Six aspects

- 1. Definition, distinctions, approximations**
- 2. Mechanisms**
- 3. Three types of treatments**
- 4. Three types of models, choices to be made, considerations**
- 5. Expressions for the energy and forces (point dipoles)**
- 6. Techniques to solve the field equations**

C. Charge-on-spring (COS) models

Equation for the induced dipoles or field equation

Induced dipoles: $\vec{\mu}_i = \alpha_i \vec{E}_i = \alpha_i \left\{ \vec{E}_i^q + \sum_{\substack{j=1 \\ j \neq i}}^N \vec{T}_{ij} \vec{\mu}_j \right\}$

Induced dipoles equation: $\vec{\mu}_i = \alpha_i \left\{ \vec{E}_i^q + \sum_{\substack{j=1 \\ j \neq i}}^N \vec{T}_{ij} \vec{\mu}_j \right\}$

Field equation: $\vec{E}_i = \left\{ \vec{E}_i^q + \sum_{\substack{j=1 \\ j \neq i}}^N \alpha_j \vec{T}_{ij} \vec{E}_j \right\}$

Equation for the induced dipoles or field equation

Using matrix notation:

$$\underline{M} = \begin{pmatrix} \vec{\mu}_1 \\ \vdots \\ \vec{\mu}_N \end{pmatrix} \quad \underline{A} = \begin{pmatrix} \alpha_1 & & & \\ & \alpha_2 & & \\ & & \ddots & \\ & & & \alpha_N \end{pmatrix} \quad \underline{T} = \text{dipole tensor}$$

$$\underline{T}_{ij} = \frac{1}{4\pi\epsilon_0} \frac{1}{r_{ij}^3} \left\{ \frac{3}{r_{ij}^2} \begin{pmatrix} x_{ij}x_{ij} & x_{ij}y_{ij} & x_{ij}z_{ij} \\ y_{ij}x_{ij} & y_{ij}y_{ij} & y_{ij}z_{ij} \\ z_{ij}x_{ij} & z_{ij}y_{ij} & z_{ij}z_{ij} \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

Induced dipole equation:

$$\underline{M} = \underline{A}\underline{E} = \underline{A}\left[\underline{E}^q + \underline{T}\underline{M}\right]$$

or

$$\left[\underline{A}^{-1} - \underline{T}\right]\underline{M} = \underline{E}^q \quad \text{so} \quad \underline{M} = \left[\underline{A}^{-1} - \underline{T}\right]^{-1} \underline{E}^q$$

Methods to solve the field equations or to find the induced dipoles

Four methods

1. **matrix inversion:** invert $\left[\underline{A}^{-1} - \underline{T} \right]$

$3N \times 3N$ matrix \rightarrow effort proportional to N^3 **expensive**

2. **iterative solution:**

$$\underline{M}^{(n)} = \underline{A} \left[\underline{E}^q + \underline{T} \underline{M}^{(n-1)} \right] \quad n = 1, 2, \dots$$

3. **use a prediction from previous MD steps (plus iteration)**

$$\vec{\mu}_i(t) = 2\vec{\mu}_i(t - \Delta t) - \vec{\mu}_i(t - 2\Delta t)$$

efficient method (combined with iteration)

Methods to solve field equations or to find the induced dipoles

Four methods

4. Treat $\vec{\mu}_i$ as additional dynamical variables

extended system technique:

Lagrangian such that $\langle \vec{\mu}_i \rangle = \alpha_i \langle \vec{E}_i \rangle$

$$L = \frac{1}{2} \sum_{i=1}^N m \ddot{\vec{r}}_i^2 + \frac{1}{2} \sum_{i=1}^N M_i^\mu \dot{\vec{\mu}}_i^2 - \frac{1}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{1}{4\pi\epsilon_0} \frac{q_i q_j}{r_{ij}}$$
$$- \sum_{i=1}^N \vec{\mu}_i \cdot \vec{E}_i + \sum_{i=1}^N \frac{\vec{\mu}_i^2}{2\alpha_i}$$

Small time step required, fluctuations induce dispersion forces

Inclusion of polarisability in molecular models

A. Why polarisability ?

- 1. Effects of polarisability**
- 2. Limitations of non-polarisable force fields**

B. Six aspects

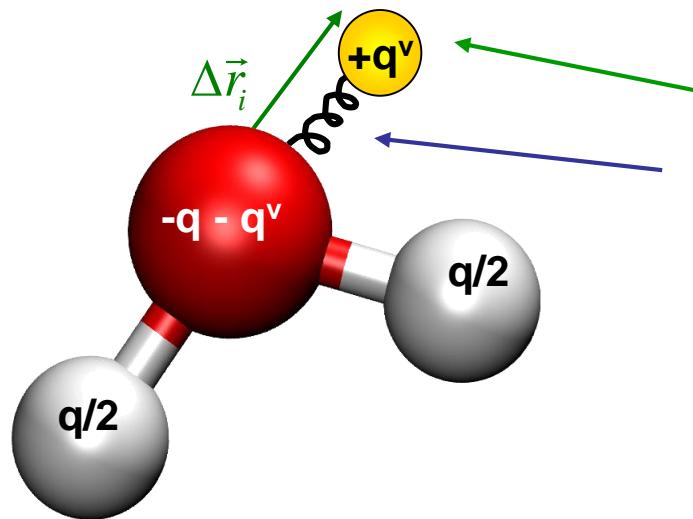
- 1. Definition, distinctions, approximations**
- 2. Mechanisms**
- 3. Three types of treatments**
- 4. Three types of models, choices to be made, considerations**
- 5. Expressions for the energy and forces (point dipoles)**
- 6. Techniques to solve the field equations**

C. Charge-on-spring (COS) models

- 1. Equations, parameters, non-linear polarisation**

The Charge-On-Spring (COS) model

The **simplest realisation of polarisation** is the **displacement** of a **charge** q^v at a **virtual (massless) site** which is **restrained by** a harmonic potential (a **spring**) to one of the real (atomic) sites or to a virtual site. Of course there is no intra-molecular Coulomb interaction.



$$\vec{\mu}_i = q_i^v \Delta \vec{r}_i$$

$$\Delta \vec{r}_i = \vec{r}_i^v - \vec{r}_0$$

virtual site

spring force constant $\frac{(q_i^v)^2}{\alpha_i}$

atom polarisability

energy: $U(\Delta \vec{r}_i) = \frac{1}{2} k_i^{ho} (\Delta \vec{r}_i)^2$

The Charge-On-Spring Model

The **virtual particle i** with charge q^v must at any time be positioned such that the **total force acting on it is zero**

$$\left. \begin{aligned} \vec{f}_i^{\text{ho}} &= -k_{\text{ho}} \Delta \vec{r}_i \\ \vec{f}_i^{\text{el}} &= q_i^v \vec{E}_i \end{aligned} \right\} \quad \vec{f}_i^{\text{ho}} + \vec{f}_i^{\text{el}} = 0$$

induced dipole $\Delta \vec{r}_i = \frac{q_i^v}{k_{\text{ho}}} \vec{E}_i$ $\vec{\mu}_i = \frac{(q_i^v)^2}{k_{\text{ho}}} \vec{E}_i$

linear polarisation: $\vec{\mu}_i = \alpha_i \vec{E}_i \rightarrow$ **force constant of spring:** $k_{\text{ho}} = \frac{(q_i^v)^2}{\alpha_i}$

Parameters of the model:

1. **site** i of charge on spring
2. q_i^v if chosen large ($-8e$) then $\Delta \vec{r}_i$ small
3. α_i polarisability

Problems with polarisable force fields

Including polarisation in a force field can lead to overpolarisation with effects such as polarisation catastrophe and too large dielectric permittivity

Some remedies:

- | | | |
|---|---|-----------------------|
| A | large enough repulsive van der Waals term | all COS models |
| B | reduced polarisability | COS/B2, COS/G2 |
| C | virtual COS site | COS/G2, COS/D2 |
| D | sublinear dependence on electric field | COS/D2 |
| E | several COS sites | expensive |
| F | screening for short distances | ad hoc |

Yu et al., *J. Chem. Phys.* 118 (**2003**) 221-234

Yu & van Gunsteren, *J. Chem. Phys.* 121 (**2004**) 9549-9564

Kunz & van Gunsteren, *J. Phys. Chem. A* 113 (**2009**) 11570-11579

Bachmann & van Gunsteren, *Mol. Phys.* 112 (**2014**) 2761-2780

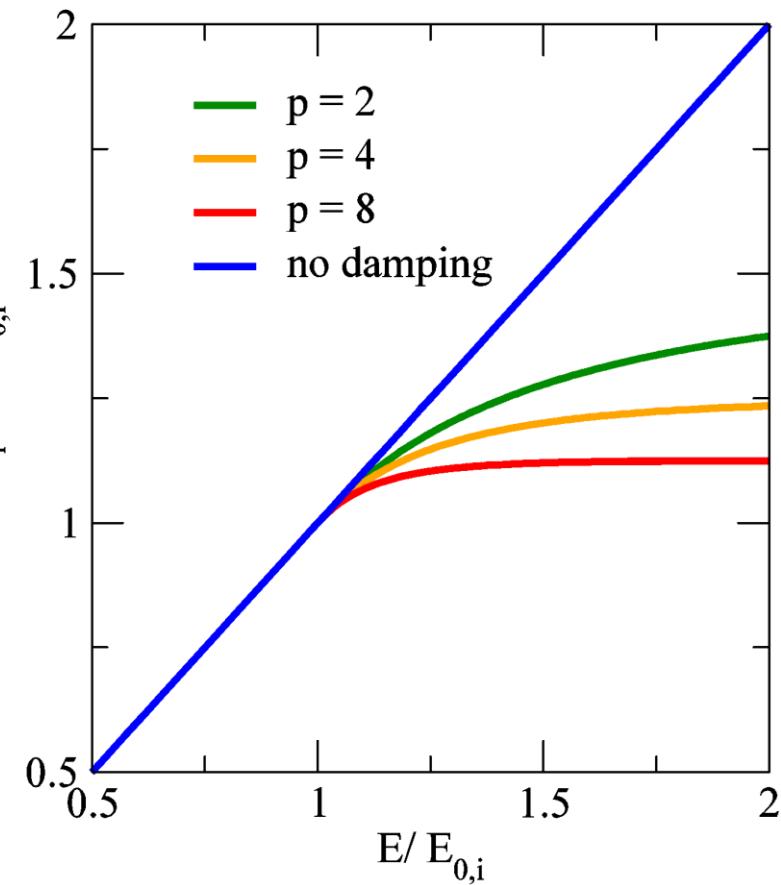
Bachmann & van Gunsteren, *J. Chem. Phys.* 141 (**2014**) 22D515

Damped non-linear polarisability

Induced dipole **linear** up to a certain value of the electric field **then levelling off** (saturation).

Continuous and continuous in the **first derivative**:

$$\vec{\mu}_i = \begin{cases} \alpha_i \vec{E}_i & |\vec{E}_i| < E_{0,i} / \alpha E_{0,i} \\ \frac{\alpha_i E_{0,i}}{p} \left[p + 1 - \left(\frac{E_{0,i}}{|\vec{E}_i|} \right)^p \right] \hat{E}_i & |\vec{E}_i| \geq E_{0,i} \end{cases}$$



Accounts for hyperpolarisability in a simplified way.

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C. Charge-on-spring (COS) models

1. Equations, parameters, non-linear polarisation
2. Applications: liquid water and other solvents

An example of a *sub-atomic* water model: The COS/D2 polarisable model

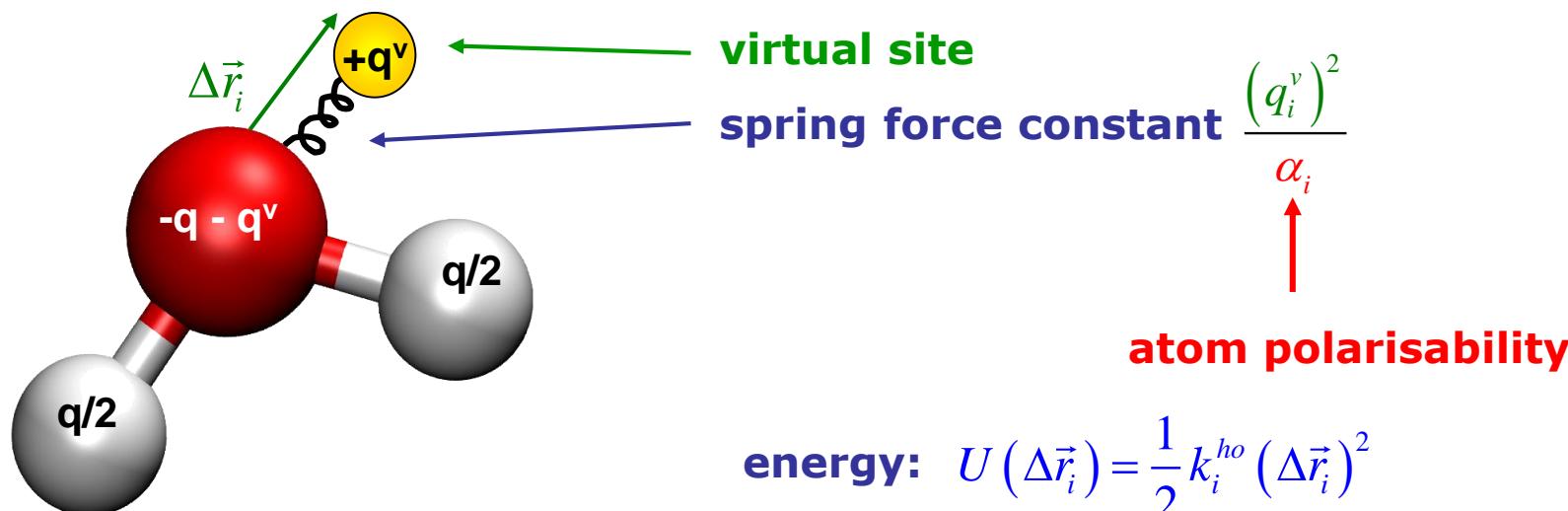
- Four-site (FG) model

The **simplest realisation of polarisation** is the **displacement** of a **charge** q^v at a **virtual (massless) site** which is **restrained by** a harmonic potential (a **spring**) to one of the real (atomic) sites or to a virtual site.

Inducible electric dipole

$$\vec{\mu}_i = q_i^v \Delta \vec{r}_i$$

$$\Delta \vec{r}_i = \vec{r}_i^v - \vec{r}_0$$



Force-field parameters: water

non-polarisable polarisable

	Exp.	SPC	COS/G2	COS/D2
C_6 (O-O) (10^{-3} kJmol $^{-1}$ nm 6)		2.617	3.244	3.2444
C_{12} (O-O) (10^{-6} kJmol $^{-1}$ nm 12)		2.634	3.458	3.252
C_{12} (H-H) (10^{-6} kJmol $^{-1}$ nm 12)				3.0
μ_0 (D)	1.855	2.270	1.850	1.855
α ($4\pi\epsilon_0 10^{-3}$ nm 3)	1.494		1.255	1.3

μ_0 increased α reduced α reduced

- Geometry: d_{OH} : 0.09572 nm $\angle HOH$: 104.52°
- Virtual site M: d_{OM} : 0.02472 nm (COS/G2 : 0.022 nm)
- Charge on spring: -8e
- Damping: p : 8 E_0 : 140 (kJmol $^{-1}$ nm $^{-3}$) $^{1/2}$

Results: thermodynamic quantities, water

non-polarisable polarisable

		Exp	SPC	COS/G2	COS/D2
ρ (kgm ⁻³)	density	997	973	999	999
ΔH_{vap} (kJmol ⁻¹)	heat of vaporisation	44.1	43.9	43.7	44.1
ΔF_{exc} (kJmol ⁻¹)	excess free energy	24.0	23.6	21.8	24.3
γ (mNm ⁻¹)	surface tension	71.6	48.4	59.0	63.6
C_p (Jmol ⁻¹ K ⁻¹)	heat capacity	75.3	93.0	107.7	88.9
α_p (10 ⁻⁴ K ⁻¹)	thermal expansion	4.22	9.0	7.0	4.9
κ_T (10 ⁻⁶ atm ⁻¹)	compressibility	45.8	47.8	47.8	44.4

ρ too small

γ too small

C_p too large

α_p too large

γ too small

C_p too large

α_p too large

γ too small

C_p too large

α_p too large

parameterised against

Results: dynamic quantities, water

non-polarisable polarisable

	Exp	SPC	COS/G2	COS/D2
D ($10^{-9} \text{ m}^2\text{s}^{-1}$) diffusion constant	2.3	4.2	2.0	2.2
τ_2^{OH} (ps) rotational correlation time	1.95	1.9	3.9	3.8

D too large τ_2^{OH} too large τ_2^{OH} too large

Results: electric quantities, water

non-polarisable polarisable

		Exp.	SPC	COS/G2	COS/D2
$\epsilon(0)$	dielectric permittivity	78.4	64.7	87.8	78.9
$\langle \mu \rangle$ (D)	total molecular dipole	2.3 – 2.5	2.27	2.61	2.55
$\langle \mu^{ind} \rangle$ (D)	induced molecular dipole	-	-	0.80	0.73
τ_D	(ps) Debye relaxation time	8.3	6.9	15.8	8.4

$\epsilon(0)$ too small $\epsilon(0)$ too large
 τ_D too small τ_D too large

Properties of non-polarisable and polarisable liquid chloroform $CHCl_3$

Properties	Experiment	Non-polarisable model (G96) 4 sites	Polarisable model (COS/C) 5 sites
ρ (kgm^{-3}) density	1489	1504	1489
ΔH_{vap} (kJmol^{-1}) heat of vaporisation	33.4	31.2	33.3
ΔF_{exc} (kJmol^{-1}) excess free energy	15.3	15.1	16.6
γ (10^{-3} Nm^{-1}) surface tension	27.2	25.8	28.7
C_V ($\text{Jmol}^{-1}\text{K}^{-1}$) heat capacity	74.7	71.7	73.5
α_p (10^{-3} K^{-1}) thermal expansion	1.26	1.44	1.29
κ_T (10^{-10} Pa^{-1}) compressibility	9.98	14.2	9.2
$\epsilon(0)$ dielectric permittivity $\epsilon(\infty)$	4.81	2.3	3.7 1.2
τ_D (ps) Debye relaxation time	5.4	4.3	5.6
D ($10^{-9} \text{ m}^2\text{s}^{-1}$) diffusion	2.3	2.4	2.2
η (cP) viscosity	0.56	0.48	0.55

Overall “better” model

parametrised against

Z. Lin et al., Mol. Phys. 108 (2010) 1749-1757
I.G. Tironi & WFvG, Mol Phys. 83 (1994) 381-403

Properties of non-polarisable and polarisable liquid CCl_4

Properties	Experiment	Non-polarisable model (G96) 4 sites (smaller system)	Polarisable model (COS/C) 5 sites (longer simulation)
ρ (kgm^{-3}) density	1594	1601	1600
ΔH_{vap} ($kJmol^{-1}$) heat of vaporisation	32.4	32.4	32.4
ΔF_{exc} ($kJmol^{-1}$) excess free energy	16.3	15.8	15.8
γ ($10^{-3} Nm^{-1}$) surface tension	26.8	28.8	28.8
$\epsilon(0)$ dielectric permittivity	2.24	1.0	2.24
D ($10^{-9} m^2s^{-1}$) diffusion	1.15	1.8	1.9
η (cP) viscosity	0.96	0.88	0.88

Better representation of dielectric response

parametrised against

A.P.E. Kunz et al., Mol. Phys. 109 (2011) 365-372
I.G. Tironi et al., Mol Sim. 18 (1996) 1-11

Inclusion of polarisability in molecular models

A. Why polarisability ?

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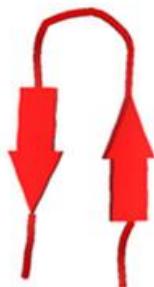
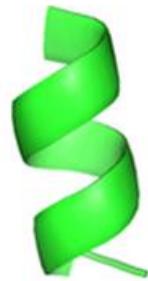
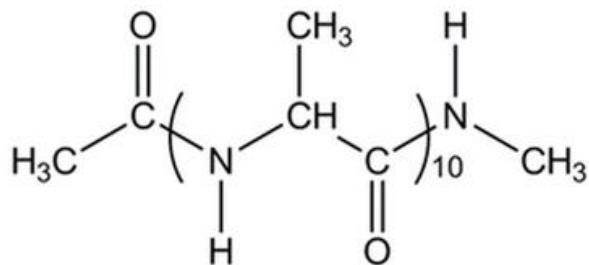
C. Charge-on-spring (COS) models

1. Equations, parameters, non-linear polarisation
2. Applications: liquid water and other solvents
3. Applications: secondary structure preferences of solutes

Stabilisation of α -helical versus β -hairpin secondary structure by polarisability of the solvent

A deca-Ala-peptide in **water**, **methanol**, **chloroform** or **CCl_4**

Free enthalpy difference between **helix** and **hairpin**
upon introduction of polarisability into the **solvent**



Solvent	Free enthalpy difference $(G^\alpha_{\text{pol}} - G^\alpha_{\text{nonpol}}) - (G^\beta_{\text{pol}} - G^\beta_{\text{nonpol}})$ [kJ mol ⁻¹]	Per residue [kJ mol ⁻¹]	Molecular polarisability α [($4\pi\epsilon_0$) 10^{-3} nm ³]
water	0.5 ± 3.7	0.0	0.93
methanol	-11.5 ± 3.5	-1.1	1.32
chloroform	-10.2 ± 1.4	-1.0	9.5
CCl_4	-21.0 ± 0.6	-2.1	11.1

Polarisability becomes more important for non-polar solvents or environments,
e.g. tails of lipids in membranes

Z. Lin & WFvG, J. Chem. Theory Comput. 11 (2015) 1983-1986

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Accounting for polarisation effects in bio-molecular simulation

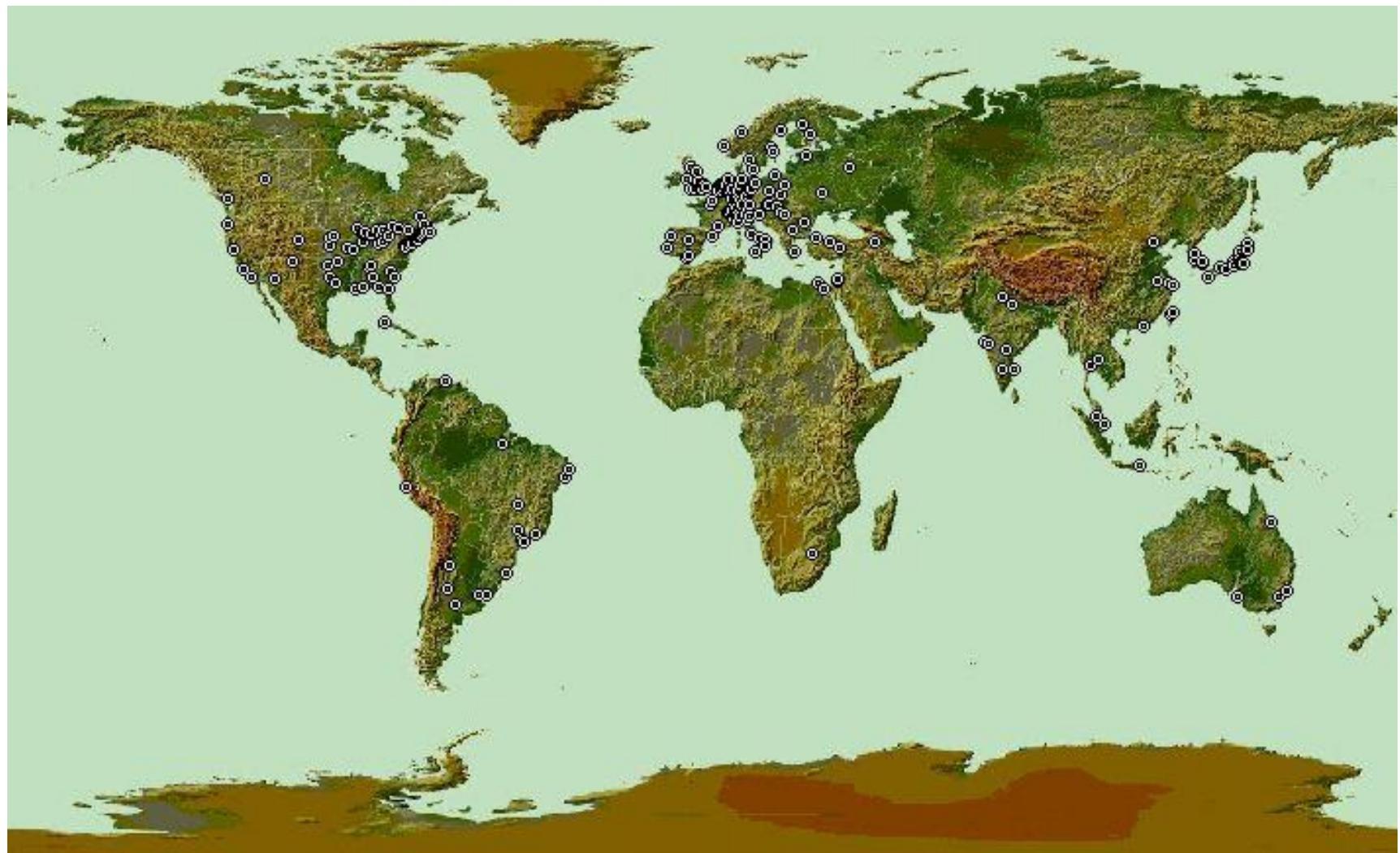
For bio-molecular solutes: proteins, DNA, RNA, ...

use quantum-chemical models,
classical polarisability models are too crude
to properly represent the electron redistribution

For solvents and lipids in membranes:

use classical (Charge-On-Spring) models,
quantum-chemical models are too expensive or inaccurate

Spatial distribution of licences GROMOS biomolecular simulation software



GROMOS = Groningen Molecular Simulation + GROMOS Force Field

Generally available: <http://www.gromos.net>